



Bangladesh Inland Water Transport Authority (BIWTA) Office of the Project Director Bangladesh Regional WaterwayTransport Project 1 (BRWTP-1) BSC Tower (Level-21), Plot # 2 & 3, RAJUK Avenue Motijheel Commercial Area, Dhaka-1000, Bangladesh

Memo No. 18.11.0000.181.14.192.21.023

Date: 01 August 2021

ADDENDUM-3

(Amendment of the Bidding Documents)

Contract Package # BRWTP-G-2: Procurement of Hydrographic Survey and Related Equipment

Ref: Bidding Documents (ICB for Goods/ Single-Stage and Single-Envelope Bidding Process) issued vide Memo No. 18.11.0000.181.14.192.21.292 dated: 05 May2021

In accordance with Instructions to Bidders (ITB) Clause ITB 8, the Bidding Documents are hereby amended as follows:

Reference of Bidding Documents (Section/ Clause)	Existing Context		Amended/ Modified Context
Section II: Bid	The deadline for bid submission is:		The deadline for bid submission is:
Data Sheet, ITB	Date: 05 August 2021		Date: 12 August 2021
Clause 22.1			Time: 14:00 Hours Bangladesh
	Time: 14:00 Hours Bangladesh Time(GMT+6 hours)	Standard	Standard Time(GMT+6 hours)
Section II: Bid The bid opening shall take place at:		The bid opening shall take place at:	
Data Sheet, ITB	to be a second to the second t		Date:12 August 2021
Clause 25.3			
	Time: 14:30 Hours Bangladesh Time(GMT+6 hours)	Standard	Time: 14:30 Hours Bangladesh Standard Time(GMT+6 hours)

Other amendments/modifications in connection with Technical Specifications for Lot-1 made in the Bidding Documents are appended below:



Lot-01: Hydrographic Survey Equipment:

Ser.	Original and/or Existing	Amended/ Modified Context	
	Context		
1.3	Swath Coverage	Swath Coverage	
	At least 10 times of water depth or up to 210°	At least 10 times of water depth or up to 210°	
	Minimum beam width	Minimum beam width	
	a. Along Track: 0.5°-0.9° b. Across Track: 0.5°-0.9°	a. Along Track:0.5°- 0.9°	
	b. Acioss Hack. 0.5 -0.9	b. Across Track: 0.5°- 0.9°	
	Real time Beam	Real time Beam stabilization	
	stabilization	Mandatory for pitch and roll	
	Mandatory for roll Rigging Arrangement	Rigging Arrangement	
	Necessary rigging	Rigging Arrangement	
	arrangements for the	Necessary rigging arrangements for the transducer and	
	transducer and pole or	pole or stave shaped Motion Sensor have to be	
	stave shaped Motion	provided. The manufacturer engineer has to calibrate	
	Sensor have to be provided. The	and fix the positions of transducer and the motion	
	manufacturer engineer has	sensors on the Purchaser's survey vessel as per instruction of the Purchaser's hydrographer.	
	to calibrate and fix the	instruction of the Purchaser's hydrographer.	
	positions of transducer		
	and the motion sensors on		
	the Purchaser's survey		
	vessel. Dynamic accuracy	BEDLUNG (
	required from MRU	MRU/INS to give	
	(deg.)	Heave: 5cm.	
	, ,	Trouvo. Com.	
-	Heave: 5cm.		
	Heading sensor	Heading sensor accuracy	
	accuracy Dynamic Accuracy ≤ 0.5°	Dynamic Accuracy ≤ 0.5°	
	. 04: Digital Hydrographic Echo-So	under (DHSE)- Single Frequency	
em No			
	Frequency	Frequency	
	200KHz, 0.5-200m Range of	200KHz, 0.5-200m Range of operation, Accuracy	
	200KHz, 0.5-200m Range of operation, Accuracy	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording	
	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey	
	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey suite as would be required, capable of sea bottom layer	
	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey	
	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey suite as would be	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey suite as would be required, capable of sea bottom layer	
	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey suite as would be required, capable of sea bottom layer etc.	
.2	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey suite as would be required, capable of sea bottom	200KHz, 0.5-200m Range of operation, Accuracy ±0.001mm+0.1% h at 1cm resolution, Self-recording and self-display, beam angle 7°, Own software survey suite as would be required, capable of sea bottom layer	



	Livioninental Condition	Operating temperature 0° to 55°C
	Operating temperature 0° to 50°C Storage temperature -5° to 55°C	Storage temperature 0° to 55°C
		Standards: IEC 60945/ EN 60068, EN 60529, CE or equivalent.
Item No	o. 05: Acoustic Doppler Current Pro	ofiler
5.2	Common Features	Common Features
	Environment: Operation: -50 to 45°	Environment: Operation: 0° to 55° C
	C and Storage: -20 to 50° C	Tilt: ±90°
	o and otorage. It to ev	and Storage: 0 to 55° C
		Compass:0-360°
	Vertical Beam	Vertical Beam
	Range: 0.2m to 80m (((±1.5),	Range:
	Resolution: 1mm	0.2m to 100m

Environmental Condition

Item No. 06: Remotely operated hydrographic survey Drone Boat

Environmental Condition

Aluminium rigid hull with an inbuilt navigation system for remote operation up to 2 km range; a maximum draft of 0.25 m, with a gross weight of approximately 45 kg (including equipment payload capacity), maximum speed of 10 knots and a duration of 6 hours.

Accuracy ±1% Resolution: 1mm

PROPULSION:	PROPULSION:
Endurance: 20 Hours at 2 knots	Endurance: 20 Hours at 2 knots
NAVIGATION AND PAYLOAD (The Drone Boat is included with Auto Nav systems and mountings only for rigging fixing of MBES & RTK GPS):	NAVIGATION AND PAYLOAD (The Drone Boat is included with Auto Nav systems and mountings only for rigging fixing of MBES & RTK GPS): n. Payload Sensors: Multibeam Echo Sounder/Sonar
n. Payload Sensors: Multibeam Echo Sounder/Sonar	
v. Max Remote operating range (m): 2000	v. Max Remote operating range (m):Minimum 2000 m
TECHNICAL SPECIFICATIONS: PHYSICAL: g. Hull Material: Aluminium	TECHNICAL SPECIFICATIONS: PHYSICAL: g. Hull Material: Aluminium Alloy.

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