# BANGLADESH INLAND WATER TRANSPORT AUTHORITY (BIWTA) 141-143, MOTIJHEEL COMMERCIAL AREA, DHAKA-1000, Bangladesh 

## No: 18.11.0000.311.14.024.2019/2967

Date: 02-03-2020
Minutes of the Pre Tender Meeting held on 19-02-2020 at 11:00 hrs. at the conference room of BIWTA Bhaban (Level-6), 141-143, Motijheel C/A, Dhaka-1000, Bangladesh in connection with the Tenders for "Procurement of 01(One) No. Pontoon-mounted Grab Dredger with DredgeMaterial Carrying Barges (GD-19)", tender No. 18.11.0000.311.14.024.2019/2589, dated:26-012020.

A Pre Tender meeting was held in the conference room of BIWTA on 19.02.2020 at 11:00am. The Meeting was presided over by the Member (Engineering), BIWTA. The Chief Engineer (Dredging) \& Project Director, Additional Chief Engineer (Marine-1), Additional Chief Engineer (Marine-2), Superintending Engineer (Mech.) \& other official concerned of BIWTA were present in the meeting. The representatives from Khulna Shipyard Ltd., PLM Cranes B.V, The Netherland, Dekker Dredging, The Netherland, TOYOTA TSUSHO CORPORAION,Japan, Posco International, N. WAVE CORPORATION \& A. C Roy \& CO, Kolkata attended the meeting.

Some questions were raised verbally and written in the meeting by the representatives of the prospective tenderers. All clarifications sought or questions raised were discussed and answered by the BIWTA officials concerned. The raised questions or sought clarifications with their corresponding answers/clarifications are given below :

| $\begin{gathered} \mathrm{Sl} \\ \text { no } \end{gathered}$ | Tender clause no | Tender Conditions given by BIWTA | Questions/Clarifications sought by the prospective tenderer | Answers/Clarificat ions |
| :---: | :---: | :---: | :---: | :---: |
| 01 | ITT clause 14.1(b)(ii) of Tender Data Sheet | The foreign reputed dredger manufacturer must submit of its at least 15 (fifteen) years of experience in manufacturing \& overseas supply of Class Grab crane/ Class Grab Dredgers/ Class Crane Barge (with proven documentary evidences). The dredger manufacturer must submit proven satisfactory performance certificate of its Class Grab crane/ Class Grab Dredgers/ Class Crane Barge which is issued by its client (s) supplied. | Requested to consider manufacturer's representative's participation. | This condition shall remain unchanged. |
| 02 | Section 6: <br> A. List of Goods and Delivery Schedule (Page no101) | Tender is floated to procure 01 (one) no. Pontoon Mounted Grab Dredger, 01 (one) no. Self-Propelled Split-Type DredgeMaterial Carrying Hopper Barge, 01(one) no. Selfpropelled Dredge material carrying Barge with other accessories. | Requested to replace "SelfPropelled Split-Type Dredge-Material Carrying Hopper Barge" by "NonPropelled Split- Type Barge". | This condition shall remain unchanged. |


| $\begin{aligned} & \mathrm{SI} \\ & \text { no } \end{aligned}$ | Tender clause no | Tender Conditions given by BIWTA | Questions/Clarifications sought by the prospective tenderer | Answers/Clarificat ions |
| :---: | :---: | :---: | :---: | :---: |
| 03 | Section 6: <br> A. List of Goods and Delivery Schedule(Pa ge no-101) | The Delivery/Completion time is given 18 (Eighteen) months from the date of signing of contract. | Requested to extend the delivery/completion time more than 36 (Thirty-six) months. | This condition shall remain unchanged. |
| 04 | 1.09 of technical specificatio n of Pontoon Mounted Grab Dredger (Page -109) | The hull of the grab dredger including its main engines, generator, electro hydraulic installations etc. shall be built and classed for 'Coastal Area' under the rules and regulations of International Classification Society <br> /NKK/ABS/DNV. of Lloyds/NKK/ABS/DNV.G | Requested to include IRS Classification Society in addition to the Classification Society of Lloyds/NKK/ABS/DNV.G L/BV. | This condition shall remain unchanged. |
| 05 | ITT clause 14.1(b)(i) of Tender Data Sheet | (i) The minimum specific experience as Supplier in supply of similar Goods (Grab Dredger/ Grab crane/ Crane Barge) of at least 1 (One) contract successfully completed within the last 5 (five) years. (i.e. years counting backward from the date of publication of IFT in the newspaper), each with a value of at least BDT 1620.00 (One thousand Six hundred Twenty) million or US $\$ 19.00$ (Nineteen) million. <br> Or <br> The minimum specific experience as Supplier in supply of similar Goods (Grab Dredger/ Grab crane/ Crane Barge) of at least 2 (Two) contract(s) successfully completed within the last 5 (five) years. (i.e. years counting backward from the date of publication of IFT in the newspaper), each with a value of at least BDT 810.00 (Eight hundred Ten) million or US\$ 10.00 (Ten) million. | Asked for a Confirmation about the Exchange Rate that may be considered for the conversion in order to substantiate the order value of similar works. | The conversion/ Exchange rate is applicable on the date of tender opening of that concerned work which will be used for determining the value of similar works by you. |



| $\begin{aligned} & \text { Sl } \\ & \text { no } \end{aligned}$ | Tender clause no | Tender Conditions given by BIWTA | Questions/Clarifications sought by the prospective tenderer | Answers/Clarificat ions |
| :---: | :---: | :---: | :---: | :---: |
|  | $\begin{gathered} \text { Mounted } \\ \text { Grab } \\ \text { Dredger } \\ \text { (Page: } 110 \text { ) } \\ \hline \end{gathered}$ |  |  | the manufacturer/ Designer for suitable dredging operation. |
| 10 | ITT Clause <br> 23.12 (d) <br>  <br> Price <br> Schedule <br> for Goods <br> (Form PG4- <br> 3B) (Page <br> No-88) | In addition to the CIF/CIP price specified in ITT 23.12(a), the price of the Goods manufactured outside Bangladesh shall be quoted: Dredger Base, BIWTA, Narayanganj, Bangladesh. <br> Price Schedule for Goods (Form PG4-3B) <br> [Group B Tenders: Goods <br> Manufactured outside <br> Bangladesh, to be imported] | Please confirm by CIP or CIF, tenderer shall quote the price of goods manufactured outside Bangladesh. | The Unit price "CIP [Chattogram port/ Mongla port] Or CIF \|Chattogram port/Mongla port|" as stated in Column-06 of Price Schedule for Goods (Form PG4-3B) shall be replaced by "CIP [Dredger Base,Narayanganj, Bangladesh]". |
| 11 | - | - | Would you allow any factor of escalation in order to evaluate a work order of previous years to bring it to the equivalence of current year, if so, please state the factor year wise for the last five years? | No, there is no scope of escalation in order to evaluate a work order of previous years to bring it to the equivalence current year. |

12. Clause 1.30 of technical specification of Pontoon Mounted Grab Dredger (Page:117) for online monitoring system will be replaced in the following manner:

The dredger shall be equipped with following online monitoring system:

## a. General Specification:

The system should have RTK (Real Time Kinematic) heading GNSS (Global Navigation Satellite System) with beacon tracking capability; inclinometers/angle sensors and on-board software which should be able to work with a RTK GNSS base station both using radio as well as cellular RTK communication. This system should be able to work with a predefined design surface providing guidance to dredger operator for accurate dredging and should be able to update and store the as-built dredging surface in real time during operation. It should provide requisite software in office to view remote dredger in real time - the views and data will be similar to what the dredge operator is viewing, that is position of dredger and cutter depth relative to the bathymetry survey and the design surface. All parts (sensors, GNSS \& \& software) shall be supplied preferably from one manufacturer. Tenderer shall submit manufacturer Authorization Letter for online monitoring system. This online monitoring system will be installed in the dredgers which are subjected to continuous dredging operation with a dredging depth up to 25 metres. Therefore, the tenderer have to submit their offer with consideration of the above matter. Details Specification has given below:

| $\begin{array}{\|l\|} \hline \mathbf{S I} \\ \text { no } \end{array}$ | Item | Quantity (unit) | Characteristics | Specification |
| :---: | :---: | :---: | :---: | :---: |
| i | GNSS Rover | 1 no. | Satellite Tracking | Should be Capable of tracking, GPS, GLONASS, GALILEO, BeiDou DGNSS Corrections via MSK Beacon Reception, 2 Channel SBAS (WAAS/EGNOS/MSAS/GAGAN) |
|  |  |  | Measuring Modes | Real-time Kinematic |
|  |  |  | Number of Channels | 400 or more |
|  |  |  | Real Time Accuracy for Kinematic |  |
|  |  |  | Horizontal | $8 \mathrm{~mm}+1 \mathrm{ppm}$ or Better |
|  |  |  | Vertical | $15 \mathrm{~mm}+1 \mathrm{ppm}$ or Better |
|  |  |  | Code Differential Accuracy | $25 \mathrm{~cm}+1 \mathrm{ppm}$ or Better |
|  |  |  | GNSS Antenna | 2 nos separate antenna with each GNSS Rover for heading. Should be able to work with MSK Beacon. To be supplied with minimum 10 meter antenna cables / required length as per design of crane Boom. |
|  |  |  | Memory | 6GB Internal memory, Should have expandable facilities through memory stick |
|  |  |  | Communication | Should have 3 serial ports or more Mini USB, Ethernet port, pps output or Better <br> Should have inbuilt Wi-Fi, Bluetooth, Radio, cellular in a single housing as GNSS Receiver. |
|  |  |  | Physical and Environmental Specification |  |
|  |  |  | Operating Temperature of GNSS Receiver | $-40^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ or Better |
|  |  |  | Storage Temperature of GNSS Receiver | $-40^{\circ} \mathrm{C}$ to $+95^{\circ} \mathrm{C}$ or Better |
|  |  |  | Shock | MIL-STD 810F or Better |
|  |  |  | Position Update Rate | 20 Hz or Better |
|  |  |  | Water and Dust | IP67 water proof, Should be Dust proof or Better |
|  |  |  | NMEA output | Support for NMEA output. |
|  |  |  | RTK Corrections data format input/output | At least RTCM 2.x, 3.x, 3.1 input \& output, CMR + CMRx |
|  |  |  | Power |  |
|  |  |  | Internal | Removable Internal battery for minimum 6 hours rover operation |
|  |  |  | External Power | 9-36 V DC external power input. Should have Overvoltage protection |
|  |  |  | System |  |
|  |  |  | On-board keyboard and display | OLED display with 4 arrow keys (up, down, left, right) and OK key or Better |


| ii |  | Dual Axis <br> Angle <br> Sensors | 1 set (Each set consists of 2 nos ) | Dual Axis Angle Sensors |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Sensor Enclosure |  | E-Coated aluminum 6061 equivalent alloy. Stainless Steel backing or Better |
|  |  | Connection Port |  | Minimum $2 \times$ Deutsch DT series 4-pin male compatible |
|  |  | Signal Output |  | CAN bus J1939.Pin 1:GND, PIN 2: V+, Pin 3:CAN Low, Pin 4: Can High or more |
|  |  | Range |  | $\begin{aligned} & +/-180^{\circ} \text { pitch, }+/-75^{\circ} \text { roll, }+/-2 \mathrm{G} \\ & \text { acceleration, }+/-200^{\circ} / \mathrm{s} \text { rate of rotation } \end{aligned}$ |
|  |  | Output Rate |  | $1,25,50,250 \mathrm{~Hz}$ configurable |
|  |  | Low dynamic tilt accuracy |  | $+/-0.1^{\circ}$ Less than 1.5 meters per second or equivalent. |
|  |  | High dynamic tilt accuracy |  | $+/-0.5^{\circ}$ |
|  |  | Dynamic Accuracy Limit |  | $300 \%$ or Better |
|  |  | Operating Vibration Limit |  | 5 G peak or Better |
|  |  | Supply Voltage |  | 9~30 V DC |
|  |  | Power Supply Protection |  | Any polarity up to 36 V |
|  |  | Environment Protection |  | IP67 or Better |
| iii |  |  | Multi Turn Cable drum Sensor | 01 set | Multi-Turn sensors |  |
|  |  | Signal Output |  |  | CANopen |
|  |  | Sensor Enclosure |  |  | Sensor Encasing should be - Wet coating (RAL 9006 white aluminium) + Cathodic corrosion protection (salt spray resistance) |
|  |  | Operating \& Storage |  |  | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
|  |  | Humidity |  |  | $98 \% \mathrm{RH}$, no condensation |
|  |  | Connection Port |  |  | $2 \times$ M12 connectors, 5 pin, male and female |
|  |  | Vibrator resistance |  |  | Vibrator resistance $<10 \mathrm{~g}$ |
|  |  | Environment Protection |  |  | IP67 |
| iv |  |  | Proximity cable drum Sensor | 01 set | Proximity Sensors |  |
|  |  | Sensor Enclosure |  |  | Should be with 2 pole Grey-coded technique |
|  |  | Signal Output |  |  | CANopen |
|  |  | Humidity |  |  | Humidity $98 \% \mathrm{RH}$, no condensation |
|  |  | Sensor Enclosure |  |  | Sensor Encasing should be Steel housing zinc plated |
|  |  | Vibrator resistance |  |  | Vibrator resistance $<10 \mathrm{~g}$ |
|  |  | Connection Port |  |  | Connection type $-5 \times \mathrm{M} 12$ connectors |
|  |  | Power |  |  | 10-30 VDC via the CAN harness |
|  |  | Operating temperature |  |  | -40 C and +70 C |
|  |  | Storage temperature |  |  | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
|  |  | Environment Protection |  |  | IP67 |
|  | v |  | Rugged <br> Computer to <br> Run On- <br> dredge <br> Marine | 01 No | Rugged Computer | Rugged vehicle type computer running windows 10 \& UPS with a separate screen with OEM specified specification to run on-dredge Marine Software with power cable carrying bag |


|  | Software |  | and other related accessories |  |
| :---: | :---: | :---: | :---: | :---: |
| vi | On Dredge Software | 01 No | The software should supports visualization and monitoring of the angle and position of the boom and crane position. |  |
|  |  |  | It also should shows the absolute position of the grab/tool in relation to the surveyed and any number of design surfaces. |  |
|  |  |  | The working surface should be updated with the dredged depths in real time and displayed in plan, profile and 3D views. |  |
|  |  |  | Over-dredge and under-dredge tolerances can be set and are visible on the profile view of the dredge head. |  |
|  |  |  | The software should support customizable interface: Multiple monitors, with independent layouts can be tailored to the needs of the dredge operator. A color-coded plan view and 3D rendering highlights high and low spots. |  |
|  |  |  | The surface Digital Terrain Model (DTM) is updated in real time registering the progress of the dredging work showing depth, differential and production models all updated according to progress of the cutter head. |  |
|  |  |  | Should support Continuous data logging for as build and volume reports. |  |
|  |  |  | Should support Dredge tolerance visualization provides guidance for accurate, efficient dredging productivity. |  |
|  |  |  | Should be configurable by Administrator who can configure the screens for a specific workflow/user and lock it down for the operator, this helping to work on a preconfigured manner without any obstacle. |  |
|  |  |  | Import or build project design and survey models in the office or field. |  |
|  |  |  | Should Supports RTK for precise tide and heave calculation. |  |
|  |  |  | Should Support Print of plans and cross sections of the dredging area being true to scale |  |
|  |  |  | Should Support Export of the data into CAD- or GIS-programmes. |  |
|  |  |  | Should Support Dredger obstacles, intermediate medium and other special features of the deposit |  |
|  |  |  | Should Support Operation Data Dashboard (visualization of dredging perform |  |
| vii | GNSS Base | 01 No | Measurements <br> Specification  |  |
|  |  |  | Satellite Tracking | Should be Capable of tracking, GPS, GLONASS, GALILEO, BeiDou or more |
|  |  |  | Measuring Modes | Real-time Kinematic |
|  |  |  | Number of Channels | 400 or more |
|  |  |  | Real Time Kinematic Accuracy |  |
|  |  |  | Horizontal | $8 \mathrm{~mm}+1 \mathrm{ppm}$ or Better |
|  |  |  | Vertical | $15 \mathrm{~mm}+1 \mathrm{ppm}$ Better |
|  |  |  | Code Differential GPS Positioning |  |
|  |  |  | Horizontal | $25 \mathrm{~cm}+1$ ppm or better |
|  |  |  | Vertical | $50 \mathrm{~cm}+1 \mathrm{ppm}$ or better |


b. Software Supply: For Dredger.

| i. | Remote Monitoring  <br> Software in Office <br> providing real time <br> field information to <br> office when field <br> dredgers are connected  <br> to office through  <br> Internet using cellular  <br> or some other  <br> communication   | $\begin{aligned} & \hline 01 \\ & \text { No. } \end{aligned}$ | Should be able to view a remote dredger operation in real-time |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | The views and data will be similar to what the dredge operator is viewing i.e position of dredger and dredging tool relative to the bathymetry survey and the design surface. |  |
|  |  |  | The office software can view individual dredgers as required. |  |
|  |  |  | Tracking of each Dredgers productivity from Office computer |  |
|  |  |  | Volume estimation of removed material |  |
|  |  |  | Monitoring of the fuel efficiency of the all operating dredgers. |  |
| ii | Computers | $\begin{aligned} & 02 \\ & \text { Nos } \end{aligned}$ | For monitoring purpose 02 (two) Computers shall be supplied by the supplier. The minimum specifications of each of the computers are as follows: |  |
|  |  |  |  | Minimum Specifications |
|  |  |  | Operating System | Windows <br> (Genuine) Professional Version |
|  |  |  | RAM | 8GB |
|  |  |  | Hard Drive (GB) | 512 GB SSD |
|  |  |  | Processor (CPU) | 64-bit processor with 4 parallel threads, Intel 5th Gen i7 or better |
|  |  |  | Display | Recommended: $1920 \times 1080$, Minimum: |



Country of origin for online monitoring system- USA/CANADA/JAPAN/EU Countries/Australia/ UK/ New Zealand/Mexico
c. Complete Local Training on GNSS RTK based Real Time Dredge Monitoring Solution for Pontoon Mounted Grab Dredgers is to be arranged for 10 (ten) BIWTA engineers for 10 (ten) days and 3 (Three) days training every 3 (Three) months up to ( 01 ) one year by the supplier's own cost through Original Equipment Manufacturer. Accommodation, food, transport and all other allowances for the trainers to be borne by the supplier.

If any Manufacturer is restricted to the above mentioned technical specification then other equivalent / better Specification of Real Time Dredge Monitoring Solution for Pontoon Mounted Grab Dredger can be offered.

13. Tenderer shall have to mention Permissible Heel Angle \& Permissible Trim Angle of Grab Dredger with the offer.
14. To excavate dredge material of irregular shape, one additional Orange Peel Grab/Bucket shall have to be supplied.
15. All other terms \& conditions in the tender document shall remain unchanged.
16. This minutes shall be the integral part of the tended document.
(Md. Abdul Matin)

Chief Engineer (Dredging)
\&
Project Director

## Distribution:

1. PLM Cranes B.V., Sluisweg 254794 SW Heijningen The Netherlands Tel: +31 (0) 167-528 510 Email: info@plmcranes.com
2. Toyota Tsusho Corporation, Tokyo Head Office 2-3-13, Konan, Minato-Ku, Tokyo, Japan. Email: takashi_komiyama@toyota-tsusho.com
3. Dekker BV, Rivierkade 3, 4931 AA, Geertruidenberg, The Netherlands, Ph: +310162570199, Email: info@dekkerdredgers.com
4. A.C. Roy \& Co.,Diamond Heritage Building, 16 Strand Road, Room No 1505, Kolkata - 700 0001, Tel: (033) 2262 8600/ (033) 6645 1291/ (033) $6645 \quad 1292$ E-mail: ho@acroyshipbuilders.in acroy55@yahoo.com.


Project Director

